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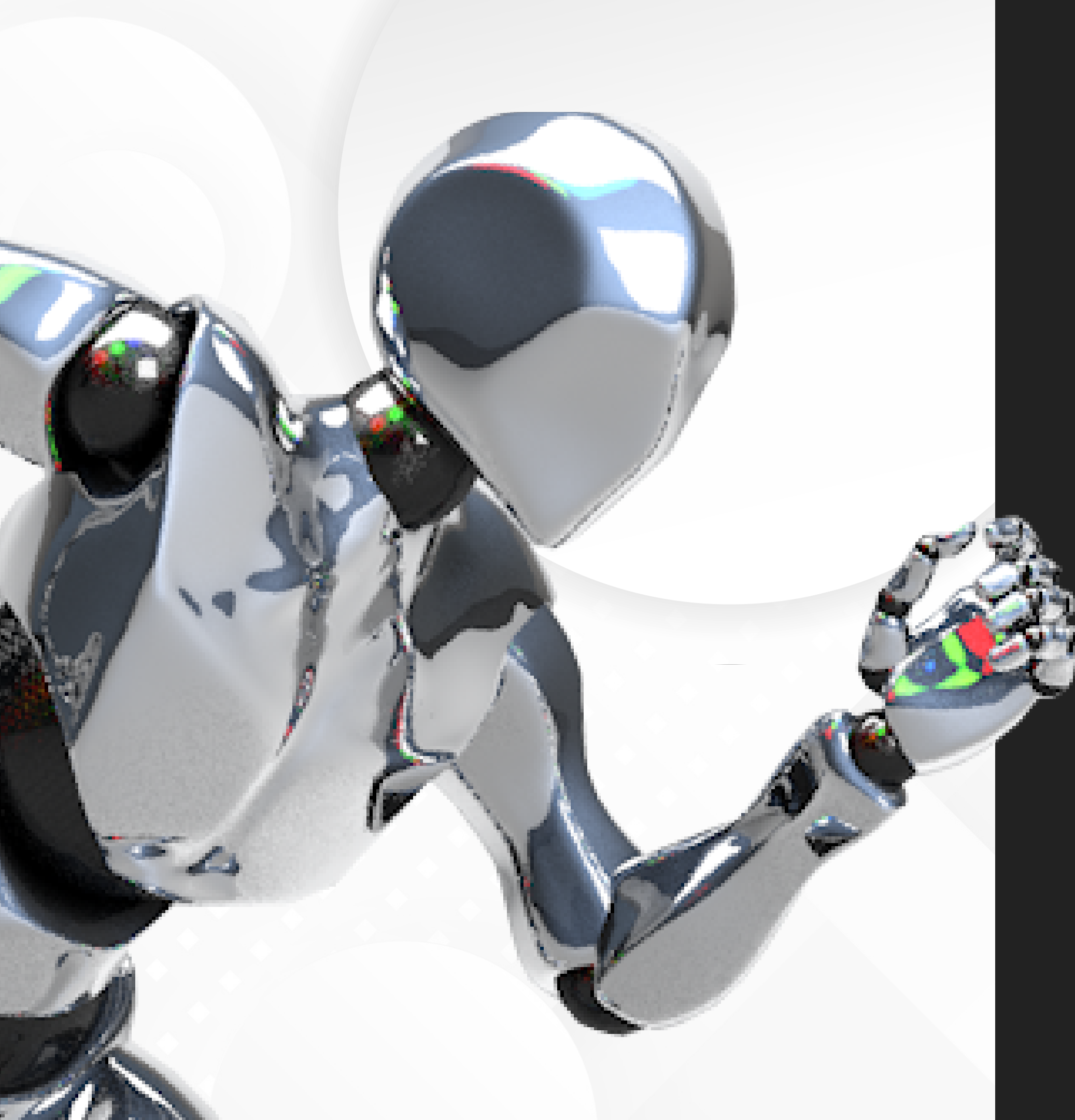
Shaping the Future of Automation and Intelligence

Organization: NOI Hackathon SFSCON Edition

7-8 November 2025

Github: <https://repos.hackathon.bz.it/2025-sfscon/team-11>





Introduction

Industrial robot monitoring & task management data centralized platform

-  Real-time robot tracking (cleaning, delivery, lifting)
-  Task assignment & monitoring
-  Performance analytics and predictions
-  Distributed desing system architecture

The team members



Ettore Miglioranza

- Role: Frontend Developer
- Skills: User interface design, web development, user experience



Matteo Massari

- Role: Backend Developer
- Skills: Server-side logic, API management, database development



Anthony Tricarico

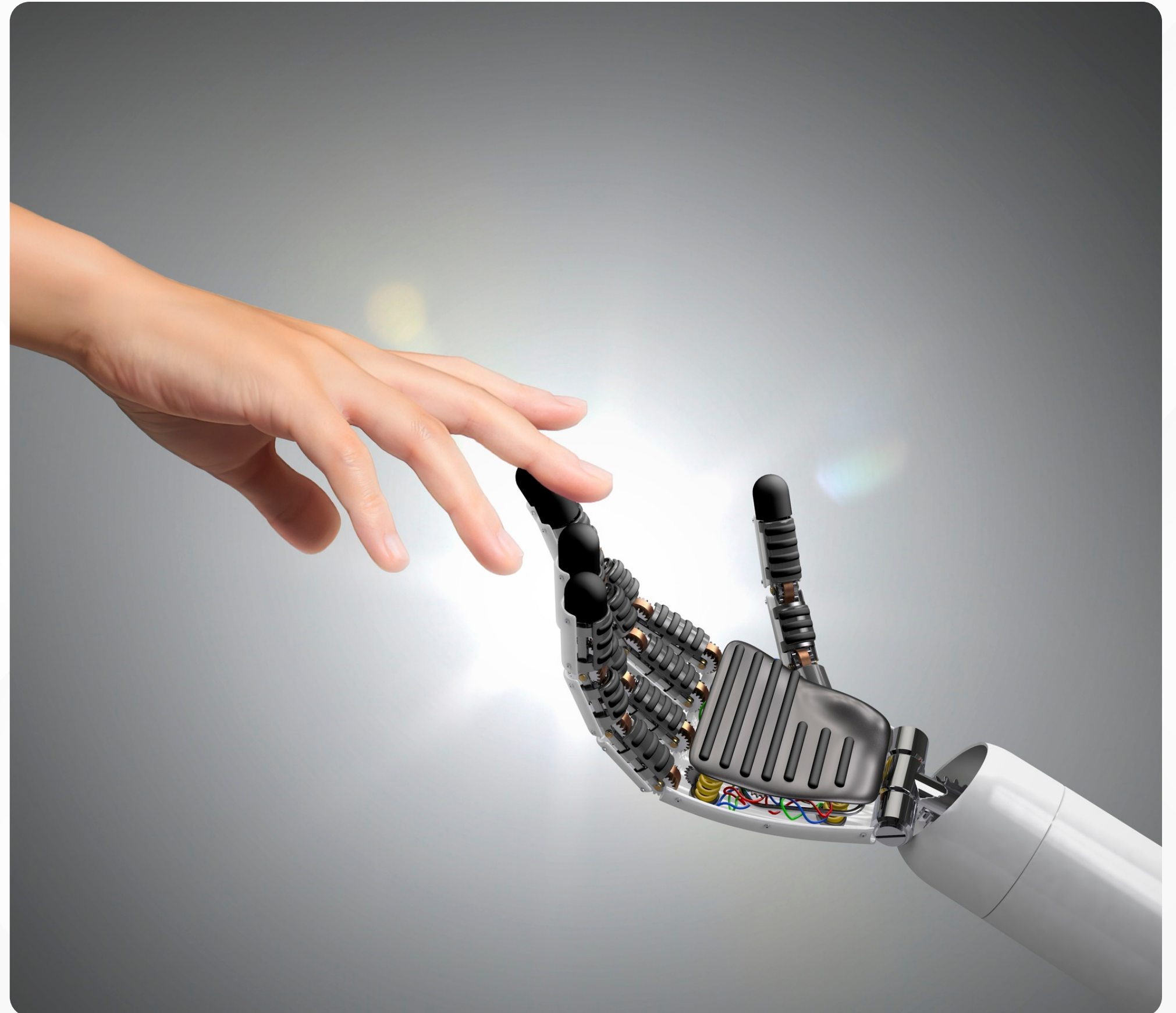
- Role: Data Analytics & Frontend Developer
- Skills: Data analysis, visualization, frontend implementation

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Centralized Multi-Robot Fleet Management Platform

How It Works

- Centralized Data Management
 - Faster query
 - structured data
 - better reporting on customer
 - Easy collection of data for ML
- Offer an experience that is tailored to the customer
 - personalized insights about robot usage
 - prescheduling of maintenance appointment with forecasting of robot maintenance

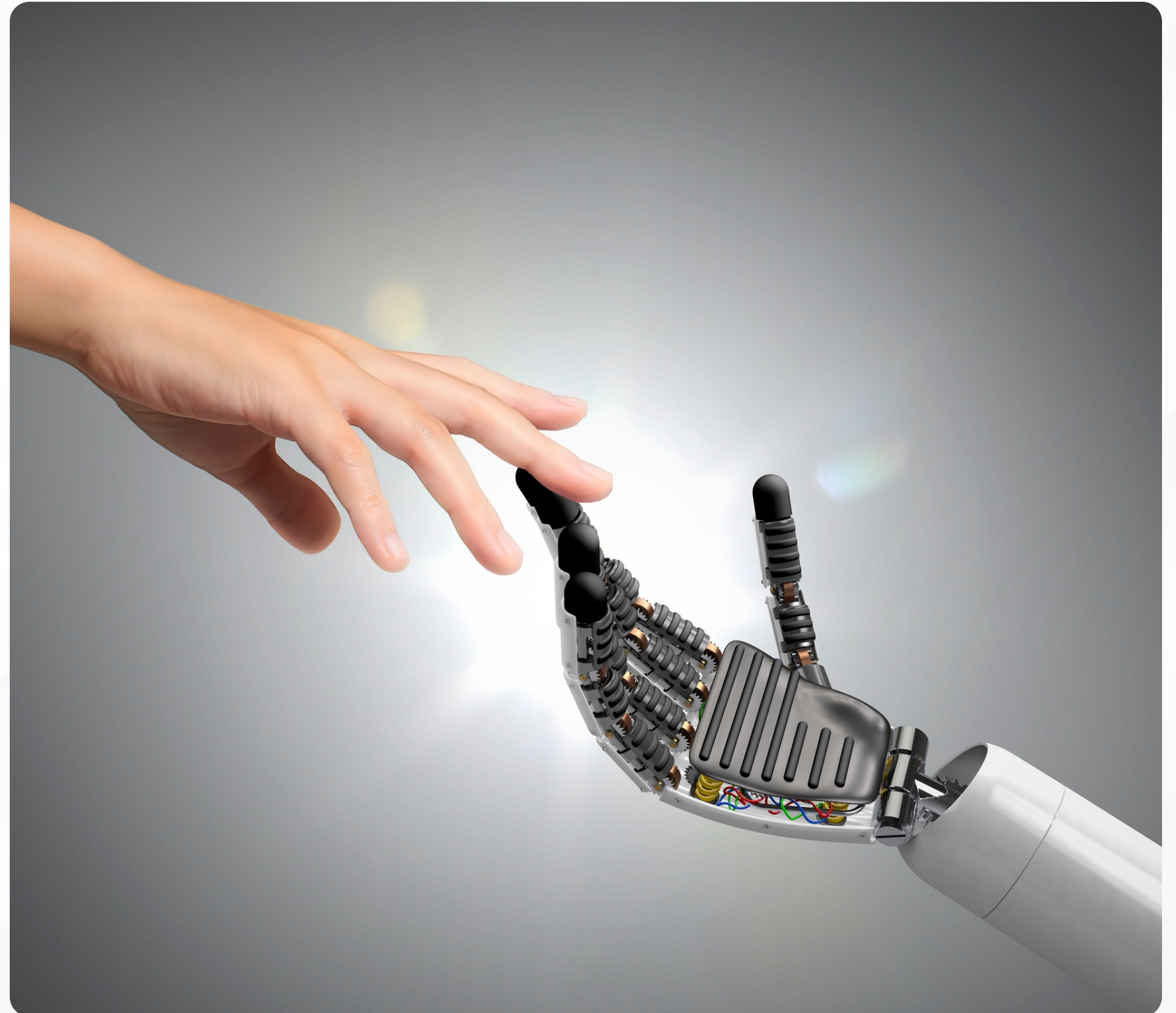


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Centralized Multi-Robot Fleet Management Platform

How It Works

- User-friendly recommendations for more efficient usage of robots:
 - automatic suggestion about furniture arrangement in the space
- Forecasting
 - time and money saving (repairing the robot before it breaks, it will cost less because it will remain in maintenance for a short period of time)
 - ML algorithm to predict the time it will take for the robot to complete a task



Methodology

Tech Stack

- Python + Streamlit – Web dashboard
- Docker – Containerization
 - for scalability and isolation
- Postgres – Structured Database
 - for structured data and easy and fast querying
- Serving layer with fastAPI
 - load distribution for the database
- Computation layer
 - perform KPI computation
 - allow prediction

